

Stepper Motors

0,65 mNm

Two phase, 20 steps per revolution

Series AM0820

Values at 20°C	AM0820	0225	0150	0080	
Nominal current per phase (both phases ON)		0,225	0,15	0,08	A
Boosted current per phase (both phases ON)		0,45	0,3	0,16	A
Nominal voltage per phase (both phases ON)		2	3	5	V
Phase resistance		7,3	18	56	Ω
Phase inductance (1 kHz)		1,4	3,9	12,6	mH
Holding torque (at nominal current in both phases)		0,65	0,65	0,65	mNm
Holding torque at boosted current		1	1	1	mNm
Residual torque, typ.		0,13	0,13	0,13	mNm
Back-EMF amplitude		0,8	1,3	2,4	V/k step/s
Electrical time constant	0,21				ms
Rotor inertia	$2,75 \cdot 10^{-9}$				kgm ²
Step angle (full step)	18				°
Angular accuracy	±10				%
Angular acceleration, max.	$363 \cdot 10^3$				rad/s ²
Resonance frequency (at no load)	75				Hz
Thermal resistance	4,1 / 65,3				K/W
Thermal time constant	3,5 / 160				s
Operating temperature range	-30 ... +70				°C
Winding temperature, max.	+130				°C
Shaft bearings ^{1) 2)}	sintered bearings (Bearing code: SB)	ball bearings, preloaded (Bearing code: 2R)			
Shaft load max.:					
– with shaft diameter	1	1			mm
– radial at 5 000 min ⁻¹ (3 mm from bearing)	0,3	3			N
– axial at 5 000 min ⁻¹	0,2	1,5			N
– axial at standstill	0,2	5,8			N
Shaft play:					
– radial	0,015	0,012			mm
– axial	0,14	0			mm
Housing material	aluminium, black anodized				
Mass	3,3				g
Magnet material	NdFeB				

¹⁾ Special lubricant options available on request.

²⁾ 2 preloaded ball bearings available on request for vacuum / low temperature (bearing code: RC).

Driver settings

Relevant for 2 phases ON only.
On PWM drivers or chopper (current mode), the current is set to the nominal value and the supply voltage is typically 2.5 to 5x higher than the nominal voltage.

Curves measured with a load inertia of $6 \cdot 10^{-3}$ kgm², in half-step mode for the "1 x nominal voltage" curve, in 1/4 micro-stepping mode for the other curves.



